Autonomous Control Level (ACL) Chart

Note: As ACL increases, capability includes, or replaces, items from lower levels

113,12	3.50				
Level	Level Descriptor	Observe	Orient	Decide	Act
		Perception/Situational Awareness	Analysis/Coordination	Decision Making	Capability
10	Fully Autonomous	Cognizant of all within Battlespace	Coordinates as necessary	Capable of total indepenance	Requires little guidance to do job
		Battlespace inference - Intent of self and others	Strategic group goals assigned	Distributed tactical group planning	Group accomplishment of strategic goal with
9	Battlespace	(allies and foes).		Individual determination of tactical goal	no supervisory assistance
	Swarm	Complex/Intense environment - on-board tracking	Enemy strategy inferred	Individual task planning/execution	
	Cognizance	·		Choose tactical targets	
	-			· ·	
8		Proximity inference - Intent of self and others	Strategic group goals assigned	Coordinated tactical group planning	Group accomplishment of strategic goal with
	Battlespace	(allies and foes)		Individual task planning/execution	minimal supervisory assistance
	Cognizance	Reduced dependance upon off-board data	Enemy tactics inferred	Choose targets of opportunity	(example: go SCUD hunting)
			ATR		
7		Short track awareness - History and predictive battlesp	Tactical group goals assigned	Individual task planning/execution to meet goals	Group accomplishment of tactical goal with
	Battlespace	data in limited range, timeframe, and numbers	Enemy trajectory estimated	individual task planning/exceution to meet goals	minimal supervisory assistance
	Knowledge	Limited inference supplemented by off-board data	Lifethy trajectory estimated		millimal supervisory assistance
	Miowieage	Elimited interestee Supplemented by oil-board data			
6	Real Time		Tactical group goals assigned	Coordinated trajectory planning and execution to meet	Group accomplishment of tactical goal with
	Multi-Vehicle	Ranged awareness - on-board sensing for long range,	Enemy location sensed/estimated	goals - group optimization	minimal supervisory assistance
	Cooperation	supplemented by off-board data	Ellerity location senseurestimated	goals - group optimization	Illillilliai supervisory assistance
	Осорегиаст	supplemented by on board data			Possible close air space separation (1-100 yds)
5	Real Time	Sensed awareness - Local sensors to detect others,	Tactical group plan assigned	On-board trajectory replanning - optimizes for	Group accomplishment of tactical plan as externally
	Multi-Vehicle	Fused with off-board data	RT Health Diagnosis; Ability to compensate for most	current and predictive conditions	assigned
	Coordination		failures and flight conditions; Ability to predict onset of	Collision avoidance	Air collision avoidance
			failures (e.g. Prognostic Health Mgmt)		Possible close air space separation (1-100 yds) for
			Group diagnosis and resource management		AAR, formation in non-threat conditions
4		Deliberate awareness - allies communicate data	Tactical plan assigned	On-board trajectory replanning - event driven	Self accomplishment of tactical plan as externally
	Fault/Event		Assigned Rules of Engagement	Self resource management	assigned
	Adaptive		RT Health Diagnosis; Ability to compensate for most	Deconfliction	V
	Vehicle		failures and flight conditions - inner loop changes		
			reflected in outer loop performance		Medium vehicle airspace separation (100's of yds)
3	Robust Response	Health/status history & models	Tactical plan assigned	Evaluate status vs required mission capabilities	Self accomplishment of tactical plan as externally
	to Real Time	,	RT Health Diag (What is the extent of the problems?)	Abort/RTB if insufficient	assigned
	Faults/Events		Ability to compensate for most control failures and		
			flight conditions (i.e. adaptive inner-loop control)		
2		Health/status sensors	RT Health diagnosis (Do I have problems?)	Execute preprogrammed or uploaded plans	Self accomplishment of tactical plan as externally
	Changeable		Off-board replan (as required)	in response to mission and health conditions	assigned
	Mission				
1	Execute	Preloaded mission data			
	Preplanned	Flight Control and Navigation Sensing	Pre/Post Flight BIT	Preprogrammed mission and abort plans	Wide airspace separation requirements (miles)
	Mission		Report status		
			-		
0	Remotely	Flight Control (attitude, rates) sensing	Telemetered data	N/A	Control by remote pilot
	Piloted	Nose camera	Remote pilot commands		
	Vehicle				
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